

MODULE DESCRIPTION

Module code	full-time studies:	Z-ZIP1-E-304					
	part-time studies:	Z-ZIPN1-E-304	(IPN1-E-304				
Module name	Mechanics for Engi	Mechanics for Engineers					
Module name in Polish	Mechanika technica	Mechanika techniczna					
Valid from academic year	2019/2020						

MODULE PLACEMENT IN THE SYLLABUS

Field of study	MANAGEMENT AND PRODUCTION ENGINEERING
Level of education	1st degree
Studies profile	General
Form and method of conducting classes	Full-time and Part-time
Specialisation	All
Unit conducting the module	Department of Production Engineering
Module co-ordinator	Dariusz Bojczuk, PhD, DSc
Approved by:	

MODULE OVERVIEW

Type of subject / group of subjects	Major
Module status	Compulsory
Language of conducting classes	English
Module placement in the syllabus - semester	Semester III
Initial requirements	No requirements
Examination (YES/NO)	NO
Number of ECTS credit points	2

Method of conducting classes		Lecture	Classes	Laborato- ry	Project	Other
Per	full-time studies:	15	15			
semester	part-time studies:	9	9			

Category	Symbol	Learning outcomes	Assignations to the directional learning out- comes
	W01	A student is knowledgeable about formulating and ana- lysing the conditions of equilibrium of force systems as well as their reduction.	ZIP1_W02
Knowledge	W02	ZIP1_W02	
	W03	ZIP1_W02	
	U01	A student is able to conduct simple static analyses in- cluding balances of force and their reduction.	ZIP1_U17
Skills	U02	A student is able to conduct simple static analyses in- cluding sliding friction and rolling resistance.	ZIP1_U17
SKIIIS	U03 A student is able to determine the setting of a centre of gravity, flat surfaces, and lines.		ZIP1_U17
	U04	ZIP1_U19	
Social competences	K01	A student understands the need of continuous improve- ment of his/her knowledge from the field of mechanics for engineers.	ZIP1_K01

TEACHING RESULTS AND THE METHODS OF ASSESSING TEACHING RESULTS

TEACHING CONTENTS

Method of conducting classes	Teaching contents
Lecture	General knowledge, elements of vector calculus, basic notions of mechanics. The laws and axioms of statics. The moment of a force about the axis, and a pair of forc- es. Bonds and the rules of releasing from bonds. Reducing a given balance of forces to a point, main vector as well as main moment, and balanced static sets. The conditions of equilibrium. The classification of types of balance of forces. Concurrent coplanar force system – equilibrium conditions, examples. Arbitrary coplanar force system – reduction of a system to a resultant (reduction con- dition), central axis equation, and continuous load – reduction to a resultant Arbitrary coplanar force system – conditions of equilibrium, examples of analysing simple and complex systems Sliding friction, developed and undeveloped friction, friction angle, cone of static fric- tion, examples. Journal friction. Band friction – developed friction relation, examples. Rolling resistance, rolling condition. Parallel force system – reduction of a system to a resultant. Gravity and mass centres – integral and total formulas. Examples of determining centres of gravity for flat surfaces and lines. Spatial force system – reduction of a system to a wrench, reduction invariants, and cases of reduction. Spatial concurrent force system – equilibrium conditions, constraints, examples. Spatial arbitrary force system – equilibrium conditions, constraints, examples.

	Revision of a vector calculus. Calculating the moment of a force about a point and axis.
	Releasing from bonds, formulating the conditions of equilibrium, and determining the reaction – concurrent coplanar force system.
Classes	Releasing from bonds, formulating the conditions of equilibrium, and determining the reaction – arbitrary coplanar force system.
	Analysing problems as regards sliding friction.
	Analysing problems regarding sliding friction, band friction, and rolling resistance
	Determining centres of gravity of solids, flat surfaces, and lines.
	Releasing from bands, formulating the conditions of equilibrium, and determining the
	reaction – spatial concurrent force system and spatial concurrent force system.

METODS OF ASSESSING TEACHING RESULTS

Symbol		Methods	of checking (se	the learning of lect X)	utcomes	
-	Oral exam	Written exam	Test	Project	Statement	Other
W01			Х			
W02			Х			
W03			Х			
U01			Х			
U02			Х			
U03			Х			
U04			Х			
K01			Х			

FORM AND CONDITIONS OF PASSING

Form of classes	Form of credit	Passing conditions
Lecture	Credit with grade	Obtaining at least 50% of the test points in the last lecture
Classes	Credit with grade	Obtaining at least 50% of test points during the class

STUDENT WORKLOAD

	Balance of ECTS points											
No.	Type of student's activity	Student's workload									Unit	
NO.			fu	II-tin	ne		part-time					Onit
1.	1. Participation in the activities		С	Lb	Ρ	0	Lc	С	Lb	Ρ	0	h
		15	15				9	9				
2.	Other (consultation, exam)	2	2				2	2				h
3.	Number of hours of a student's as- sisted work		34			22				h		
4.	Number of ECTS credit points which are allocated for assisted work	1,4			0,9				ECTS			
5.	Number of hours of a student's un- assisted work	16			28				h			
6.	Number of ECTS credit points which a student receives for unassisted work		0,6			1,1				ECTS		
7.	Work input connected with practical classes			25			25					h
8.	Number of ECTS credit points which a student receives for practical classes	1,0			1,0				ECTS			
9.	Total number of hours of a stu- dent's work	50 50					h					
10.	Punkty ECTS za moduł 1 ECTS=25 hours	2							ECTS			

LITERATURE

- 1. Hendzel Z., Żylski W. (2016), *General mechanics. Statics,* Oficyna Wydawnicza Politechniki Rzeszowskiej, Rzeszów
- 2. Beer F., Johnston Jr., Eisenberg E., Mazurek D. (2009), *Vector mechanics for engineers: statics,* Mc Graw-Hill Science
- 3. Meriam J. L., Kraige G., Bolton J. N. (2019), *Engineering Mechanics: Statics SI Version*, John Wiley and Sons (JL)